

# INTEGRATED CIRCUIT WITH BIT ERROR TEST CAPABILITY

## BACKGROUND OF THE INVENTION

[1] The present invention relates to integrated circuits.

[2] Integrated circuits (ICs), such as field programmable gate arrays (FPGA) or application specific integrated circuits (ASIC), usually comprise an input unit (also referred to as input cell or input block) to receive an input signal from external with respect of the integrated circuit, a processing unit (also referred to as logic core) to receive and process the sampled comparator output signal, and an output unit to receive a data signal from the processing unit, to derive therefrom an output signal, and to provide the output signal to external with respect of the integrated circuit. The input unit generally comprises a level comparator for comparing the level of the input signal and correspondingly providing a comparator output signal, and a sampling unit (e.g. flip-flop) coupled to the level comparator for sampling the comparator output signal. Typically, the IC has multiple input units and/or multiple output units but may also only have one input and/or output unit.

## SUMMARY OF THE INVENTION

[3] It is an object of the invention to provide an improved integrated circuit. The object is solved by the independent claims. Preferred embodiments are shown by the dependent claims.

[4] According to the present invention, a bit error test unit is provided for bit error testing using already existing facilities of the integrated circuit. The invention thus allows providing bit error testing directly and within the IC, so that the testing actually 'sees' what the IC 'sees' e.g. in contrast to having to wire out dedicated measuring points e.g. onto a printed circuit board (PCB) carrying the IC. Accuracy of the bit error testing can thus be increased. Using already existing facilities of the integrated circuit also reduces signal

influencing by the testing itself and thus adversely affecting signal performance.

[5] This allows to have bit error test capabilities e.g. behind every pin of an ASIC or FPGA, therefore system tests can be performed, which include the 'whole' environment of the IC, like the PCB or other circuits, which may have impact on the signal integrity of the entire system. From this follows that embodiments of the invention allow to calculate timing and/or level margins for those systems. Having this knowledge can lead to savings regarding e.g. design cycle time and NPI (new product introduction) processes.

[6] The invention can be partly embodied or supported by one or more suitable software programs, which can be stored on or otherwise provided by any kind of data carrier, and which might be executed in or by any suitable data processing unit. Software programs or routines are preferably applied in order to process the collected data from the bit error test and e.g. display the results preferably as bit error test scan, eye diagram or spectral jitter curve.

#### MORE DETAILED DESCRIPTION OF PREFERRED EMBODIMENTS ACCORDING TO THE INVENTION

[7] Other objects and many of the attendant advantages of the present invention will be readily appreciated and become better understood by reference to the following detailed description when considering in connection with the accompanied drawing.

[8] Fig. 1 shows an example of a preferred embodiment of an IC 10 according to the present invention. The IC 10 comprises an input unit 20 to receive an input signal SIG from external with respect of the IC 10. The input unit 20 comprises a level comparator 30 for comparing the input signal SIG and correspondingly providing a comparator output signal COS to a sampling unit 40 for sampling the comparator output signal COS.

[9] The level comparator 30 can be any circuit allowing comparing levels of signals. In case of a single-ended input signal SIG, the level comparator 30 preferably compares the input signal SIG, or a signal derived therefrom, as comparator input signal against a threshold value. Such threshold can be e.g.  
5 a reference potential, or toggle point of the input unit 20, etc.

[10] In case of a differential input signal SIG, the level comparator 30 preferably compares a normal signal of the differential comparator input signal against a complementary signal of the comparator input signal, with the complementary signal being complementary to the normal signal. Level-shifting  
10 might be applied between the differential signals in order to change the crossing point between the normal and complementary signals.

[11] The level comparator 30 might provide as comparator output signal COS a value (e.g. a digital '1' or 'HIGH' signal, or a digital '0' or 'LOW' signal) depending on the corresponding level comparator inputs. In case of single-  
15 ended signals, the level comparator 30 might provide as comparator output signal COS a first value (e.g. a digital '1' or 'HIGH' signal) in case the comparator input signal is greater than the threshold value and a second value (e.g. a digital '0' or 'LOW' signal) in case the comparator input signal is smaller than the threshold value. Level shifting might be applied here in order to  
20 connect the following circuits behind the level comparator (e.g. sampling unit).

[12] A processing unit 50 receives and processes the sampled comparator output signal SAM from the output of the sampling unit 40. An output unit (not shown in the figures) receives a data signal OUT from the processing unit 50, derives therefrom an output signal (not shown in the figures), and provides the  
25 output signal to external with respect of the IC 10.

[13] Thus, the input unit 20 receives and samples the input signal SIG for further processing by the processing unit 50, which again outputs and communicates the processed output signal OUT to external via the output unit.

It is clear that input and output units can be separated (e.g. unidirectional, for example in an address bus application) or provided by a common input/output (I/O) unit (e.g. bidirectional, for example in a data bus application).

5 [14] The processing provided by the processing unit can be any kind of data processing such as any combinatorial operation, retiming or just routing a signal across the IC, cross point switching, providing Arithmetic Logic Unit (ALU), providing memory cells, etc.

[15] The IC 10 itself can be of any function or purpose as known in the art.

10 [16] The sampling unit 40 might comprise double data rate (DDR) and single data rate (SDR) circuits. The phase shifting unit 70 might comprise delay locked loop (DLL) or phase locked loop (PLL) circuits or any other facility that allows variable clock data alignment (shifting) in order to change the sampling time e.g. with respect to the external (data) signal.

15 [17] Further in Fig. 1, a bit error test unit 60, preferably controlled in operation by a control unit 65, also receives the sampled comparator output signal SAM and determines therefrom an indication of a bit error in a sequence of the sampled comparator output signal (SAM). For that purpose, the bit error test unit 60 might determine the number of bits within an interval from the comparator output signal SAM and the number of errors detected in the same interval. E.g. dependent on its processing abilities, the bit error test unit 60 might further determine a value of bit error rate (BER), representing the ratio of erroneous digital signals (Bits) to the total number of regarded digital signals, e.g. dividing the determined number of errors by the corresponding detected number of bits in the sampled comparator output signal SAM. The details of bit error testing are well-known in the art, as disclosed e.g. by the applicant in EP-  
20 A-1241483 and European Patent Application Nos. 02017334.0 and 02017333.2, and need not be illustrated herein. The teaching of those documents shall be incorporated herein by reference.

[18] The bit error test unit 60 might determine the number of errors (detected for the number of bits) or the value of the bit error rate by comparing the sampled comparator output signal against an expected pattern. This expected data pattern might be derived from an internal (e.g. inside unit 60) pattern generator, can be stored in the memory 80, can be a comparator output signal provided from external (not shown), derived using a reference path as illustrated in the aforementioned European Patent Application No. 02017333.2, or derived otherwise as known in the art. The number of bits and errors are preferable determined by using accumulators and counters as known in the art.

[19] A phase shifting unit 70 receives a clock signal CLK and provides to the sampling unit 40 a phase-shifted clock signal CLKP for controlling a sampling point of the sampling unit 40. The phase-shifting of the phase shifting unit 70 is controlled by the control unit 65 as indicated by control line CTR. For the sake of clarity it is mentioned that the phase shifting unit 70 does not necessarily have to phase-shift the clock signal in a specific measurement (i.e. representing a zero phase shift), however, allows to modify the sampling point by phase-shifting the clock signal, so that different sampling points can be selected for the bit error measurements.

[20] The bit error indication (e.g. number of bits, the number of errors detected for the number of bits, and the value of the bit error rate) are preferably determined with respect to the sampling point (preferably representing a point in time relative to transition time of the clock signal), so that bit error measurements for sampling points be determined (e.g. for determining the so-called eye-diagram or parts thereof in the direction of the time axis).

[21] In one embodiment, the control unit 65 further allows controlling the level of the level comparator 60, so that bit error measurements for different levels can be determined (e.g. for determining the so-called eye-diagram or parts thereof in the direction of the signal level axis).

[22] The clock signal CLK may be provided from external of the IC 10 or generated internally by the IC 10. The clock signal CLK may also be derived from a data signal such as the input signal SIG or any other signal derived therefrom. This can be achieved using data clock recovery units as well known in the art (as will be explained later for unit 200).

[23] In the embodiment of Fig. 1, the bit error test unit 60 is further coupled to a memory 80 allowing to buffer and/or store data provided from the bit error test unit 60. It is clear that the memory 80 might also be integral part of the bit error test unit 60.

[24] The determined bit error test indication (e.g. number of bits of the measurement interval, the determined number of errors detected for the number of bits, and/or the determined value of the bit error rate) can be stored and/or buffered in the memory 80, e.g. for later processing or communicating to other units.

[25] Further coupled to the bit error test unit 60, either directly or via the memory 80, preferably there is a interface unit 90, which allows to couple to an external bit error test processing unit 100 being external with respect to the IC 10. The interface unit 90 might be, for example, a Joint Test Action Group – JTAG - Boundary Scan Interface, or any other interface allowing communication with external.

[26] The interface unit 90 is also coupled to the control unit 65 allowing to control operation of the control unit 65 e.g. by the external bit error test processing unit 100.

[27] The interface unit 90 might also communicate to the external bit error test processing unit 100 e.g. status information of the bit error test unit 60, the determined number of bits, the determined number of errors detected for the number of bits, or the determined value of the bit error rate. The interface unit

90 might also receive control signals from the external bit error test processing unit 100 allowing controlling and initiating operation of the bit error test unit 60 (as indicated by the arrow from the interface unit 90 to the bit error test unit 60.

5 [28] In case of high speed applications, the sampling unit 40 can be embodied by a deserializer for deserializing the (high speed) comparator output signal COS to a lower speed signal. The sampling unit 40 is preferably embodied by a limiting amplifier as known in the art.

10 [29] The IC 10 might further comprise a clock data recovery unit 200 for deriving the clock signal CLK from a data signal. In the example of Fig. 1, the clock data recovery unit 200 derives the clock signal CLK from the comparator output signal COS, however, it might also use the comparator input signal, the input signal, or another signal derived from the input signal accordingly. The phase shifting unit 70 is coupled to the clock data recovery unit 200 and receives the recovered clock signal CLK therefrom. Instead or in addition, the  
15 IC 10 might also use the signal recovery scheme as outlined in the aforementioned European Patent Application No. 02017334.0.

[30] A clock divider 210 might be coupled to the output of the phase shifting unit 70, it might be also part of the serializer – deserializer unit. An output of the clock divider 210 can be coupled to the bit error test unit 60 and/or other  
20 units (not shown in Fig. 1) in order to allow processing the data inside those units at the same speed the sampling unit is running.

[31] While the various blocks in Fig. 1 are depicted as individual units, it goes without saying that one or more of those blocks can be combined or provided as integral parts.